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SENSUM Earth Observation Tools Medium Resolution algorithms

USER MANUAL

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List of acronyms

ACRONYM	DESCRIPTION
MR	Medium Resolution
HR	High Resolution

Document Purpose

Purpose of this document is to provide a concise user manual related to the version of the SENSUM Earth Observation tools implemented into the G-POD infrastructure.

This manual is addressed to people familiar with interpretation of medium resolution optical satellite imagery.

SENSUM Earth Observation tools

EO-based exposure and vulnerability proxies can be defined at different spatial levels. Extension and outline of a built-up area, for example, is a valuable piece of information when assessing exposure to various natural risks on a vast area. Zooming into the urban areas, other proxies can be defined like buildings regularity and density, height, shape etc. Different open-source C and Python libraries are already available for image processing and geospatial information handling (e.g. OrfeoToolbox, OpenCV and GDAL) providing basic processing tools, producing results that reach a point located one step behind the exposure target. Therefore, it is of significant importance to provide end-users with a set of tools based on simple work flows capable of returning information at a higher level, in other words to “include the last mile”.

The research group at the University of Pavia developed a set of python algorithms, integrating low-level image processing techniques with exposure-oriented workflows. This set of tools is available as QGIS plugin¹ and source code². Details related to each function can be found on the online SENSUM EO tools user guide³.

Following, the complete list of algorithms including a brief explanation of each algorithm and the resolution the algorithms can focus on (medium or high resolution).

Table 1. List of algorithms available through the QGIS plugin

ICON	NAME	DESCRIPTION	MR/HR
Pan	Pan-sharpening	Pan-sharpening algorithm from OrfeoToolbox.	MR and HR
Cla	Classification	Unsupervised/Supervised classification from OrfeoToolbox.	MR and HR
Seg	Segmentation (including optimizer option)	Segmentation algorithms from OrfeoToolbox, TerraAIDA (InterImage) and Skimage (python library).	MR and HR
Fea	Features	Computation of spectral and textural features from segments.	MR and HR
Cor	Co-Registration	Co-registration algorithm designed for medium resolution. SURF and FFT alternatives are included. While services of Open CV library are used in our approach, the FFT algorithm comes from Numpy (python library).	MR
Stck	Stack satellite	Stack satellite workflow including co-registration and built-up extraction with 4 different methodologies.	MR
Chg	Unsupervised change detection	Automatic analysis of the outcome of the object-based built-up area extraction algorithms.	MR

¹ https://plugins.ggis.org/plugins/sensum_eo_tools/

² https://github.com/SENSUM-project/sensum_rs_ggis

³ <http://ldt.unipv.it/sensum-docs/>

Extr	Footprints extraction	Supervised extraction of building footprints.	HR
Hgt	Building height	Combination of shadows and footprints with acquisition date for height extraction.	HR
Den	Building density	Calculation of the density of building in an area of interest.	HR
Reg	Building regularity and alignment	Computation of alignment and regularity of buildings.	HR

G-POD integration

From the set of algorithms proposed before, the MR-oriented workflows have been chosen to be integrated as G-POD service. The idea is to take advantage of the direct link with the Landsat and Sentinel catalogues.

NOTE: Landsat and Sentinel-2 data cannot be processed together.

Stack Satellite

The processing workflow “backbone” is unchanged in respect of the QGIS plugin. Major adjustments have been carried out in order to parallelize tasks and take advantage of the available worker nodes. Details related to the implementation can be found in *De Vecchi et al., 2016⁴*.

5 different methods are integrated to extract built-up areas from MR imagery:

- Built-up Index method is based on an index computed using green, NIR and IR bands; the result is a raster layer called “built_up_index.tif” with 5 bands (SAVI, NDVI, NDBI, MNDWI and BUILT_UP). The built-up area can be extracted by applying a threshold over the last band. The same raster layer is also used as input for the segmentation (see Dissimilarity method and PCA OB method).
- PCA index method is a combination of PCA bands; the result is a raster layer called “pca_index.tif” with 1 band related to the computed index. The built-up area can be extracted by applying a threshold.
- PCA classification method is the result of an unsupervised classification with PCA bands as input. The built-up area usually corresponds to one or two classes.
- PCA OB method⁵ is the combination of PCA bands averaged within segments computed over “built_up_index.tif” from the most recent input year. Segments are then classified using an unsupervised approach.
- Dissimilarity method⁶ is based on the computation of the dissimilarity texture over the area of interest and the consequent combination with segments. The outcome is classified using an unsupervised classification.

All the methods present above are available as input parameters along with:

- Cloud cover threshold: percentage of cloud cover allowable. Data with cloud cover exceeding this value will not be processed.
- Segmentation parameters [spatial radius, range radius, threshold, max iterations, min size]: input parameters of the ‘Meanshift’ segmentation. Check the Orfeo Toolbox cookbook for more details related to the algorithm⁷. Default values are provided.
- Number of classes: number of classes for the unsupervised classification. Default value is 5.
- DEM: use SRTM 30 meters DEM to mask mountains out.

⁴ D. De Vecchi, F. Dell’Acqua, R. Cuccu, C. Orrù and G. Rivolta, “Integration of tools for Large-Scale Exposure and Vulnerability assessment into the Remote Geospatial Processing Environment of the European Space Agency: an experience on “SENSUM Tools”, ESA Big Data from Space Conference (BiDS’16), Tenerife, Spain, 15-17 March 2016.

⁵ D. De Vecchi, M. Harb and F. Dell’Acqua, “A PCA-based hybrid approach for built-up area extraction from Landsat 5, 7 and 8 datasets”, Geoscience and Remote Sensing Symposium (IGARSS), 2015 IEEE International, Milan, 2015, pp. 1152-1154. doi: 10.1109/IGARSS.2015.7325975

⁶ M. Harb, D. De Vecchi and F. Dell’Acqua, “Automatic hybrid-based built-up area extraction from Landsat 5, 7, and 8 data sets”, *Urban Remote Sensing Event (JURSE), 2015 Joint*, Lausanne, 2015, pp. 1-4. doi: 10.1109/JURSE.2015.7120475

⁷ <https://www.orfeo-toolbox.org/CookBook/CookBooksu127.html#x159-9680004.9.8>

Unsupervised Change Detection
TO BE IMPLEMENTED SOON

Create a SENSUM Stack Satellite task

1. Connect to the following website: <http://gpod.eo.esa.int/>
2. Log into the G-POD portal using your EO-SSO Login information
3. Click on 'Land' and then jump to the second page or simply type 'sensum' in the search bar
4. Click on the 'SENSUM' service



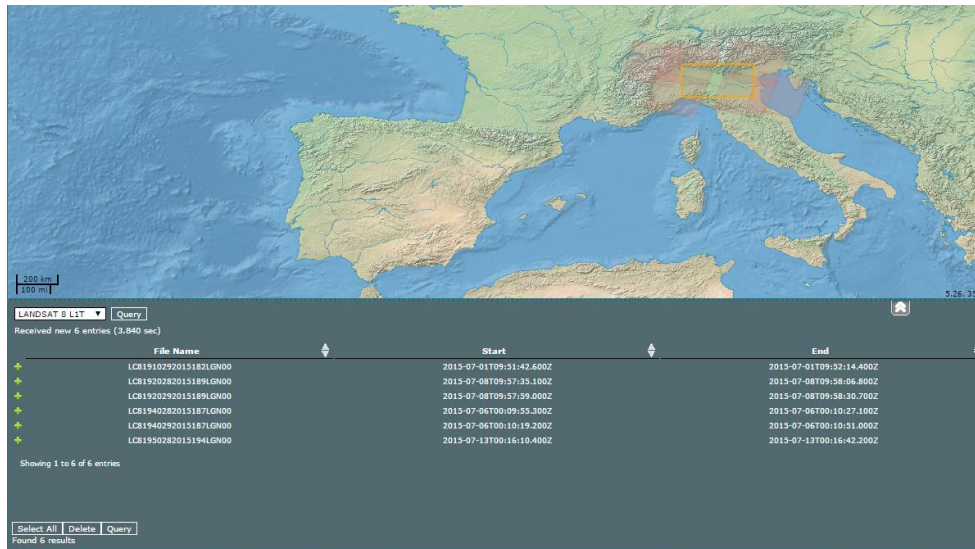
5. Define an AOI on the map (yellow rectangle), specifying also the time period



6. Select the catalogue to query ('LANDSAT 8 L1GT', 'LANDSAT 8 L1T', 'LANDSAT-7 ETM+ GTC', 'SENTINEL-2 MSI L1C')



7. Click on the 'Query' button
8. From the provided list, select the data to be processed (CTRL+click)
 - a. [Suggestion] try to select data with homogeneous acquisition time covering the AOI
 - b. The algorithm automatically merges all the tiles necessary to fill the AOI
 - c. Multiple years can be selected and processed separately



9. Fill the parameters box

- Cloud cover threshold: images with Cloud Cover exceeding these values will not be processed
- Segmentation parameters: default values are provided
- Number of classes: used as input of the unsupervised classification, default is 5
- Select/deselect the methods to be applied
- Select/deselect the DEM option (default is true)

Processing Parameters

[Here you can download and consult the SENSUM User Manual.](#)

SENSUM Processor

Cloud Cover Threshold [%]

DEM

Number of Classes

Built Up Index Method

PCA Index Method

PCA Classification Method

PCA OB Method

Dissimilarity Method

Segmentation Parameters

10. Click 'Save in Workspace' if you want to add more datasets or check the parameters. Click 'Process it' to start immediately the procedure.



11. Status of the process and other details can be checked by clicking on the 'Workspace' tab. The next paragraph is dedicated to the 'Workspace' section.

Check and download the results

Information related to the status of the procedure can be found in the 'Workspace' section.

The screenshot shows the 'Workspace' section of the ESA grid processing on demand interface. It features a navigation menu at the top with options like Home, Services, Workspace, Catalogue, Products, Schedulers, My profile, and Documentation. A search bar is present with the text 'Showing the 2 results found'. Below the search bar, there is a table with columns for 'Caption', 'Service', 'Computing Resource', 'Status', 'Creation time', 'Submission time', and 'Completion time'. The table contains two rows of data, both with a 'Completed' status. Below the table, there are buttons for 'Delete', 'Abort', 'Re-submit', and 'Rebuild and Re-submit'.

Click on caption name to explore the details

The screenshot shows the 'SENSUM processing' details page. It has a progress bar at the top with three steps: '1- DATA SELECTION', '2- PROGRESSING STATUS', and '3- RESULTS VISUALIZATION'. The main content area is divided into two sections. The left section contains metadata for the task, including Task ID, Services, Status, Progress, Creation Time, Submission Time, Completion Time, Processing ID, and CE. The right section features a world map with a scale bar (2000 km and 2000 mi) and a coordinate system (189.25, 18.00). Below the map is a table with columns for 'Result Identifier', 'Start Time', and 'End Time'. The table contains one entry with the URL 'http://gpod.eesa.int/aea1c882-32af-4f87-92c3-c7c22076de6c', a start time of '2015-02-01T00:00:00', and an end time of '2016-02-28T12:01:16'. Below the table, there is a 'Task Operations' section with a 'Caption' field containing 'SENSUM processing' and buttons for 'Copy', 'Clone', 'Recreate', 'Resubmit', 'Request Input Data', and 'Delete'. At the bottom, there is a 'Jobs Information' button.

SENSUM

1- DATA SELECTION 2- PROGRESSING STATUS 3- RESULTS-VISUALIZATION

SENSUM processing

Task ID: 3849390a-76e4-4bc0-a005-69b897881be9
 Service: SENSUM
 Status: Created (refresh) Cost: 1
 Progress: 0%
 Creation Times: 2016-03-08T10:06:02 (UTC)
 Submission Times:
 Completion Time:

[DataHandler](#) -> [StackSatellite](#) -> [publish](#)

Task Operations

Priority: **Normal** ▼
 Computing Resource: **ITER CE** ▼
 Publish Server: **Portal** ▼ Compression: **None** ▼ Caption: **SENSUM processing**

[Copy](#) [Clone](#) [Recreate](#) [Submit](#) [Request Input Data](#) [Delete](#) [Modify](#)

[Jobs Information](#)

Press the 'Jobs Information' button

Jobs Information

DataHandler

[Details](#) [Input](#) [Parameters](#) [Processing Nodes](#)

[6277] [0/1] wnode13 Last notification: [2016-03-07T10:44:40 (UTC)]
 6277_stdout
 6277_stderr
 sensum_log


[Resubmit](#)

StackSatellite

[Details](#) [Parameters](#) [Processing Nodes](#)

Status: Completed
 Progress: [0/1] 100%
 RESOURCES: 0 computing nodes

Additional Information: stackSatellite processing concluded




publish

[Details](#) [Parameters](#) [Processing Nodes](#)

Status: Completed
 Progress: [0/1] 100%
 Resources: 0 computing nodes

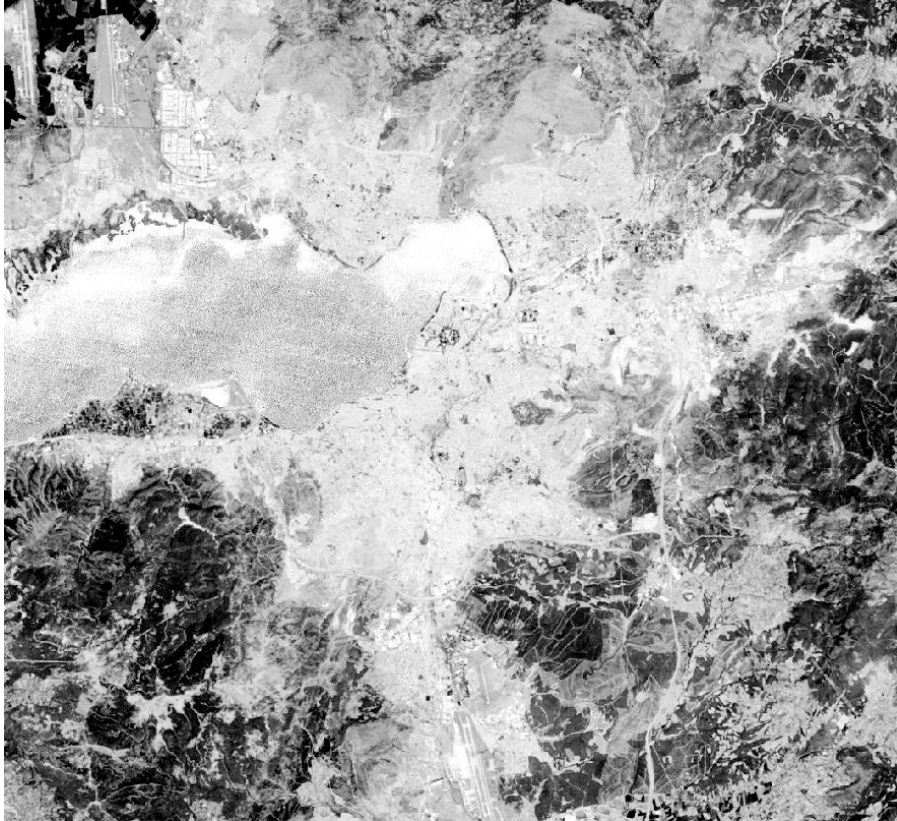
Additional Information: publish processing concluded



Results interpretation

Every result can be downloaded and further refined using software like QGIS.

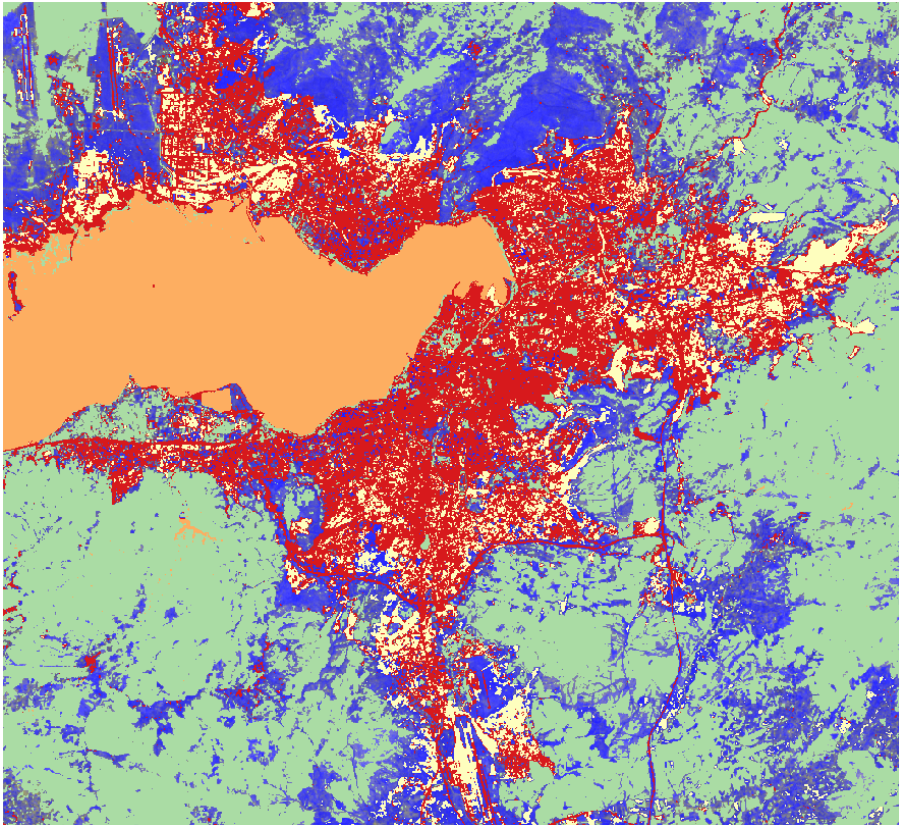
- Built-up index method



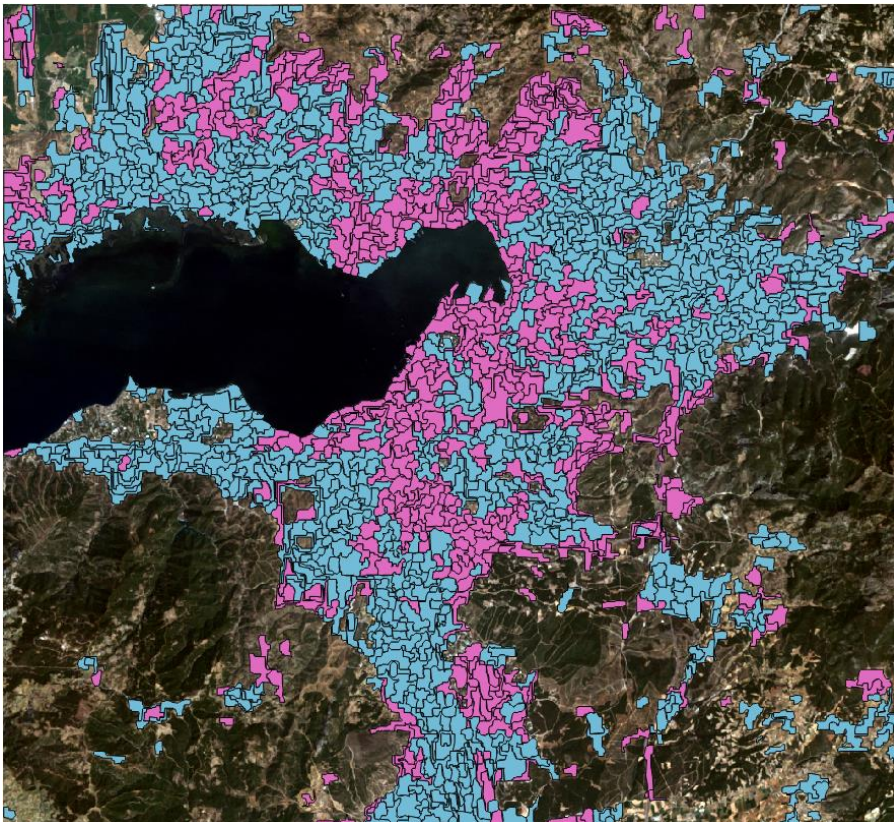
- PCA index method



- PCA classification method



- PCA OB method



- Dissimilarity method

