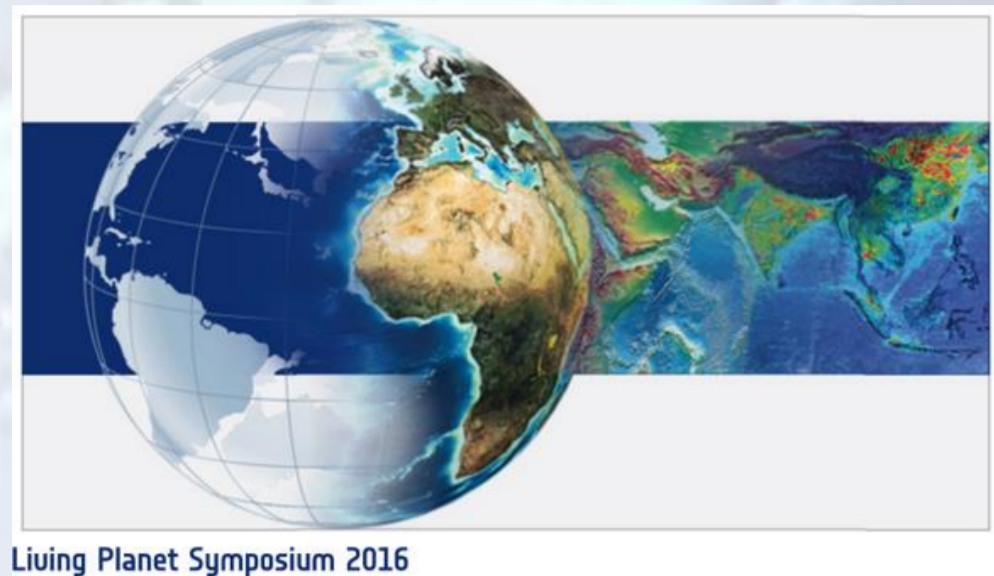


# MEETC2: Ocean Color Atmospheric corrections in coastal complex waters using a Bayesian latent class model and potential for the incoming Sentinel 3 - OLCI mission



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## Abstract

- ❖ From top-of-atmosphere (TOA) observations, atmospheric correction aims at distinguishing atmosphere ( $\rho_{aer}$ ) and water contributions ( $\rho_w$ ). In coastal areas the water and aerosol spectra may show some similarities. In these areas, a priori on the variable distributions to be estimated are needed to correctly unmix the signals and **converge towards positive & realistic estimates**.
- ❖ From a methodological point of view, our algorithms MeetC2 relies on a Bayesian inference using Gaussian Mixture Model prior distributions on reference spectra of  $\rho_{aer}$  and  $\rho_w$  [1].
- ❖ Associated with the water normalised reflectance estimates,  $\rho_{nw}$ , a **total uncertainty**  $\sigma_{\rho_{nw}}$ , i.e. a combination of the TOA level 1 reflectance uncertainty and the Bayesian inversion uncertainty is provided for each pixel.

## Numerical experiment

- ❖ The MERMAID (<http://mermaid.acri.fr/home/home.php>) in-situ matchup database is a comprehensive dataset that gathers in-situ measurements of water leaving radiances, IOPs, and MERIS TOA reflectances. To validate the proposed methodology, the radiometric in-situ profile dataset has been divided randomly in two independent datasets: a training dataset (to estimate the model parameters) and a validation dataset [1].

### Validation of the inverted $\rho_w(\lambda)$ with an independent matchup dataset.

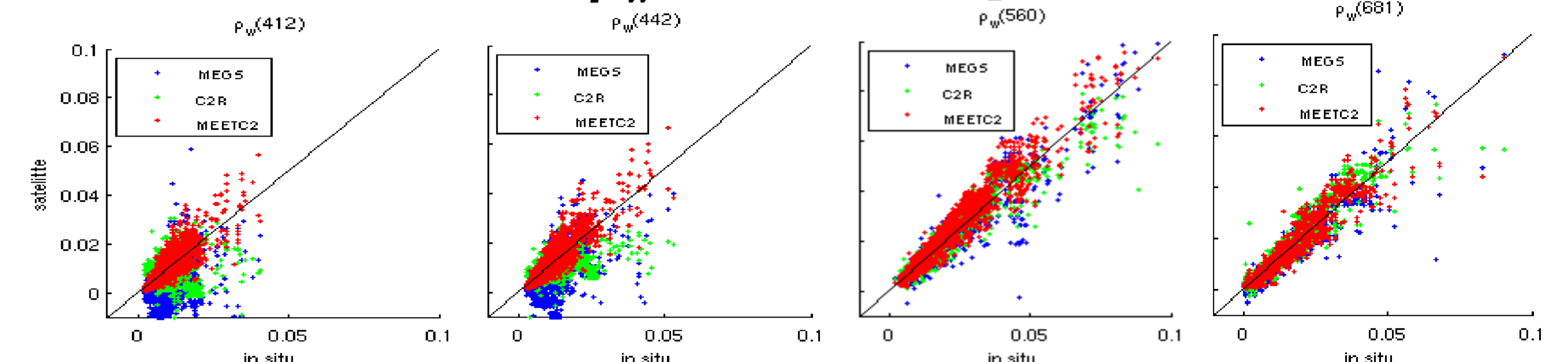


Figure 2: comparisons between the estimated  $\rho_w$  at 412, 442, 560 and 681 nm using MEETC2 vs in-situ (red), MEGS 8 vs in-situ (blue) and C2R (NN) vs in-situ (green) [1].

## MeetC2 functional Scheme

- ❖ We consider the classical multiple scattering radiative transfer equation and start from the Rayleigh corrected reflectance variable  $\rho_{RC}(\lambda)$  [1]:  

$$\rho_{RC}(\lambda) = \rho_{gc}(\lambda) - \rho_{Ray}(\lambda) = \rho_{aer}(\lambda) + t_d(\lambda) \cdot \rho_w(\lambda) + \rho_{coupl}(\lambda) + \varepsilon \quad (1)$$
  - ❖ Bayesian model introduces priors on the variable to be estimated and resort to maximise the a posteriori likelihood (MAP criterion):  

$$P(x_a, x_w | \rho_{RC}, \varphi_a, \varphi_w) \propto P(\rho_{RC} | x_a, x_w, \varphi_a, \varphi_w) \cdot P(x_a | \varphi_a) \cdot P(x_w | \varphi_w) \quad (2)$$
- where  $X_a$  = the polynomial coefficients of the aerosol models [1].  
 $X_w$  = the coordinates of  $\rho_w$  in the reference basis [1].  
 $\varphi_w = \{\rho_w(780), c, \Theta_v, \Theta_s, \delta\psi\}$ , observed or pre-estimated covariates (step 1, Figure 1) conditioning the a priori shape of the water reflectance spectrum to be estimated [1].  
 $\varphi_a = \{\rho_{aer}(865), c, \Theta_v, \Theta_s\}$ , observed or pre-estimated covariates (step 1, Figure 1) conditioning the a priori shape of the aerosol reflectance spectrum to be estimated [1].
- ❖ Figure 1 summarises the 4 steps involved in the atmospheric correction MEETC2 Bayesian inversion.

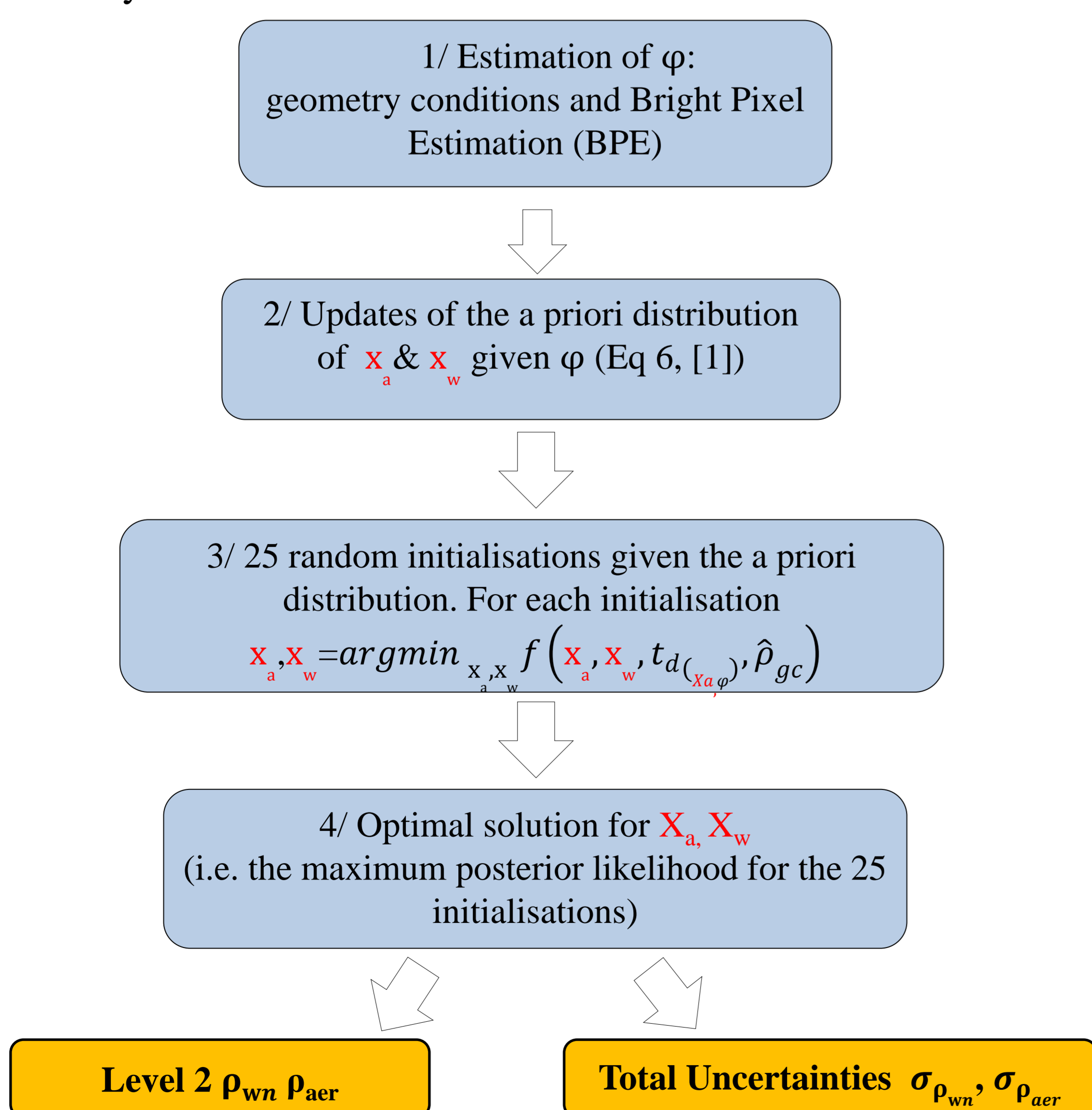


Figure 1: operational scheme for the atmospheric correction MEETC2 Bayesian inversion.

### Comparisons of the inverted $\rho_w(\lambda)$ with state-of-the art algorithms.

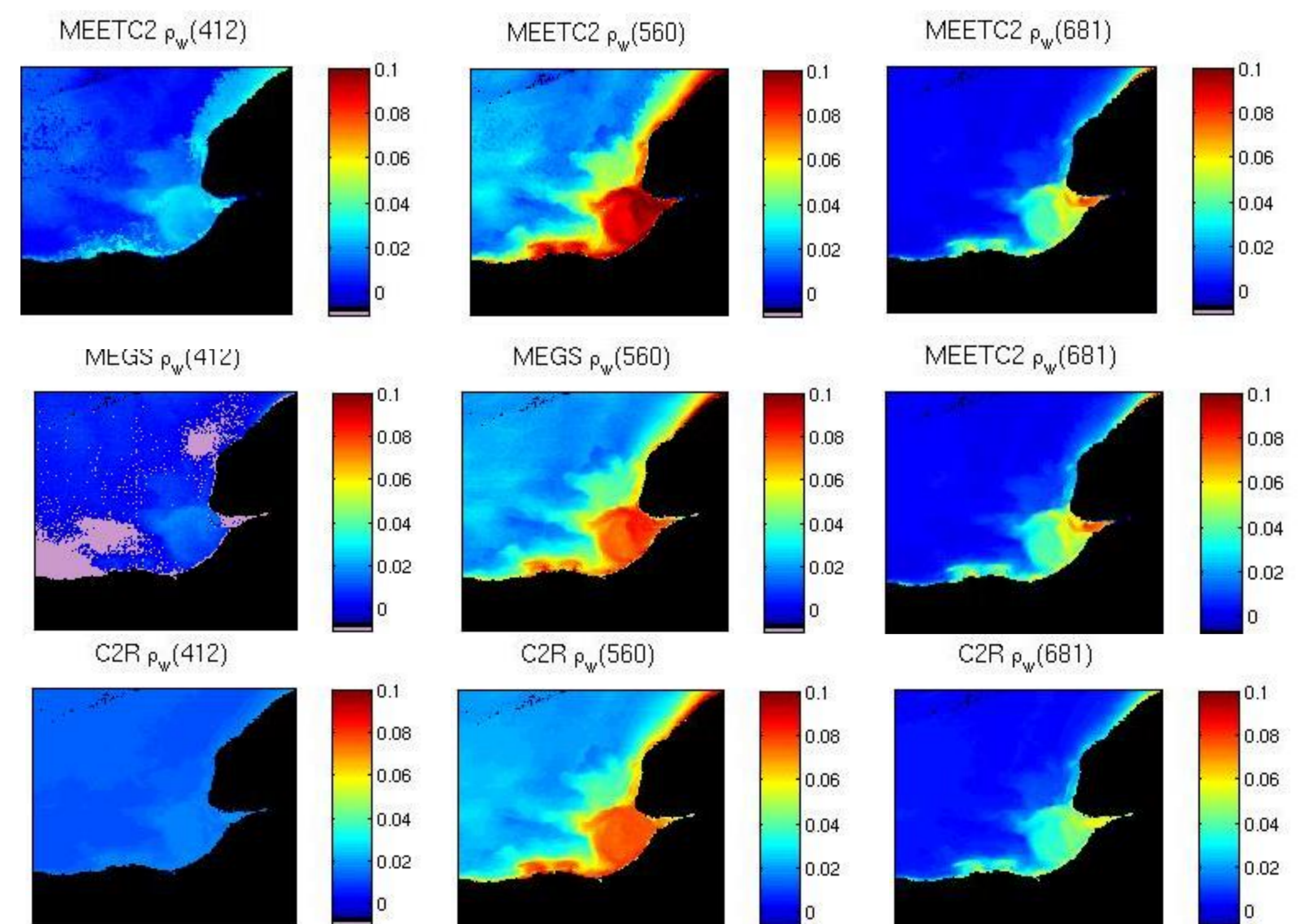


Figure 3: Estimated  $\rho_w(412, 560, 681)$  from the MERIS FR Level 1 image of the 20040209 over the French river La Seine's estuary. Top, MEETC2 retrievals, middle, MEGS v8 and bottom C2R retrievals. In pink are highlighted negative reflectances.

## Towards an operational algorithm for OLCI

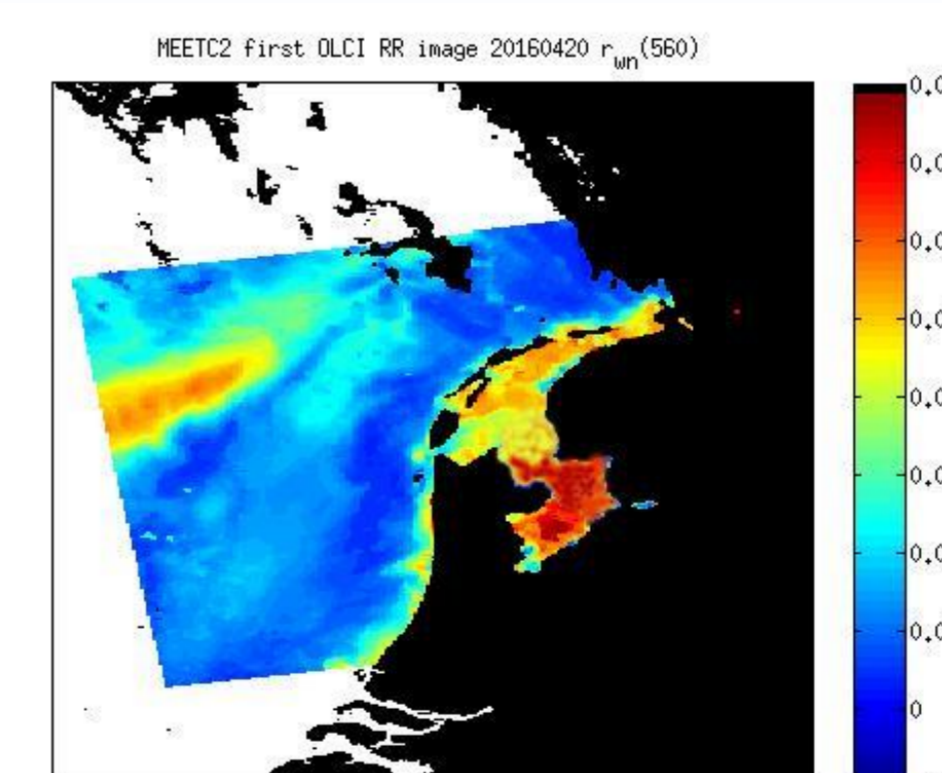


Figure 4: A first result (not verified) of the MEETC2 atmospheric correction using the OLCI RR image of the 20 April 2016 over the Baltic Sea.

- ❖ The ambition of a Case1&2 algorithm to inverse operationally the OLCI water leaving reflectances: the Bayesian formalism is particularly suitable to address transitions between water types and **avoid negative estimates in coastal turbid areas**.
- ❖ The natural observed variability of the aerosol (water) variables, conditioned by the geometry conditions and the concentration of aerosols (water optically active constituents), will be addressed using **radiative transfer simulations**.
- ❖ The quasi-randomised initialisations (Figure 1, step 3) involve multiple inversions for each pixel leading to high computational costs. Consequently, a parallelised implementation of MEETC2 will be developed.

